MAGNETIC FLUID-BASED SQUEEZE FILM BETWEEN CURVED POROUS ANNULAR PLATES CONSIDERING THE ROTATION OF MAGNETIC PARTICLES AND SLIP VELOCITY

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Abstract

The ferrofluid flow model of the Shliomis and continuity equation for the film and porous interface with the theory of Darcy, the modified Reynolds equation for ferrofluid squeeze film between curved annular plates are discussed with the impact of the rotation of Ferro-particles and slip velocity at the boundary. Beavers and Joseph's slip conditions are adopted to study the impact of slip velocity. The generalized non-dimensional pressure equation is derived and expression for dimensionless load-carrying capacity is obtained for the same. The graphical representation suggests that the bearing's performance enhances due to ferrofluid, considering the appropriate values of parameters for slip velocity and porosity.

Keywords: Shliomis' Magnetic fluid flow model, annular plates, porosity, slip velocity, load carrying capacity (LCC).

1. Introduction

In bearings, annular plates are one of the most important structural components used in industrial applications and engineering fields. They are broadly used in the production of aircraft, ships, automobiles and other vehicles. The squeezing action of the approaching surfaces causes fluid to flow toward less constrained surroundings.

A ferrofluid is synthesized in the lab and it represents a liquid that becomes strongly magnetized in the presence of a magnetic field, with friction-reducing capabilities. In recent years, ferrofluid has had many industrial applications, because of the increased use of liquid metal lubricants at high temperatures. The slip velocity depends mainly on the difference in density between the two fluids and their holdups.

In the last three decades, several researchers have analyzed the effect of magnetic fluids in various bearings with squeeze film phenomena such as Kumar et al. (1992) in spherical and conical bearings, cylindrical rollers by Sinha et al. (1993), Lin (2001) for parallel annular disks, Shah and Bhat (2005) in an infinitely long journal bearing, Shah and Bhat (2004) for annular plates, Patel and Deheri (2013) in circular plates, parallel plate rough slider bearing by Patel and Deheri (2016), Hanumagowda et al. (2018) in annular plates and short bearing by Munshi et al.

(2019). They suggested that the negative effect can be easily nullified by the positive impact of the squeeze film occurrences and ferrofluid. It improved the MHD squeeze film characteristics of the system.

As per the literature, a porous medium is a well-known phenomenon to improve bearing systems' effect. Many authors dealt with the performance of porous medium in various magnetic fluid lubricated bearing systems: Agrawal (1986) in inclined slider bearing, Bhat and Deheri (1991) for composite slider bearing, annular discs by Bhat and Deheri (1991), Bhat and Deheri (1993) for circular discs, Shah and Bhat (2000) in circular plates, annular plates by Shah et al. (2002), Patel and Deheri (2014) in curved circular plates, Deheri et al. (2016) convex pad slider bearing and Vasanth et al. (2018) for the annular plate. It was examined that the load-bearing capacity was affected by the porous medium.

Nowadays, many investigators (Bujurke et al. (2007), Shimpi and Deheri (2013), Deheri and Patel (2015), Patel and Deheri (2016) and Shah et al. (2016)) motivated to prob on annular plates due to their extensive applications in various engineering fields. They have examined that we can improve the bearing's presentation by choosing suitable parameters (for instance, slip velocity, porosity, roughness, etc.). Shah and Patel (2017) discussed the ferrofluid lubricated circular discs porous squeeze film bearings with the impact of porosity, slip velocity, anisotropic permeability and rotation. It was detected that the unchanging magnetic field did not move on the demonstrations of the bearing systems. Mishra et al. (2018) studied an inclined slider bearing considering surface roughness, porosity and magnetic field effect. It was investigated that the slip parameter's adverse effect, reported in earlier studies over load-lifting capacity, turned rather sinusoidal to be encouraging, which might be due to the shape of the variation of a Ferro-field.

In the present paper, magnetic fluid's effect with the rotation of magnetic particles and slip velocity on squeeze film between curved porous annular plates has been theoretically examined.

2. Mathematical Formulation

As in Figure 1, the bearing is made of two annular disks with outside radius a and inside radius b(a>b).



Fig. 1. Configuration of the Problem

The film thickness h is considered as Murti (1975)

$$h = h_0 e^{-\beta r^2}, b \le r \le a \tag{1}$$

Where r, h_0 and β are radial coordinate, central film thickness and the upper plate's curvature, respectively. Two plates approach with a normal velocity $\dot{h} = \frac{dh}{dt}$.

Ferro particles can relax in two ways as the applied magnetic field changes described in Shliomis (1972) and Kumar (1989). One is by the Brownian relaxation time parameter τ_B . Another is by the relaxation time parameter τ_s .

Assuming steady flow, neglecting inertia and the second derivative of the internal angular momentum \overline{s} without assumptions of Shukla and Kumar (1987), the equation for fluid flow of Shliomis (1972) can be governed by

$$-\nabla p + \eta \nabla^2 \overline{q} + \mu_0 \left(\overline{M} \cdot \nabla \right) \overline{H} + \frac{1}{2\tau_s} \nabla \times \left(\overline{S} - I \overline{\Omega} \right) = 0$$
⁽²⁾

$$\overline{S} = I\overline{\Omega} + \mu_0 \tau_s \left(\overline{M} \times \overline{H} \right), \tag{3}$$

$$\overline{M} = M_0 \frac{\overline{H}}{H} + \frac{\tau_B}{I} \left(\overline{S} \times \overline{M} \right), \tag{4}$$

Where *p* is the pressure, η being the viscosity of the suspension, μ_0 stands for the permeability of free space, \overline{H} is the applied magnetic field, \overline{M} be the magnetization vector, \overline{q} indicates the fluid velocity, *I* is the sum of moments of inertia of the particles per unit volume, $\overline{\Omega} = (1/2)\nabla \times \overline{q}$, and M_0 is the equilibrium magnetization, together with continuity equation,

$$\nabla . \bar{q} = 0 \tag{5}$$

And equations of Maxwell

$$\nabla \times H = 0 \tag{6}$$

$$\nabla \cdot \left(\bar{H} + \bar{M} \right) = 0 \tag{7}$$

Using equation (3), we observe that equation (2) and (4) reduces to

$$-\nabla p + \eta \nabla^2 \overline{q} + \mu_0 \left(\overline{M} \cdot \nabla \right) \overline{H} + \frac{1}{2} \mu_0 \nabla \times \left(\overline{M} \times \overline{H} \right) = 0$$
(8)

and

$$\overline{M} = M_0 \frac{\overline{H}}{H} + \tau_B \overline{\Omega} \times \overline{M} - \frac{\mu_0 \tau_B \tau_s}{I} \overline{M} \times \left(\overline{M} \times \overline{H}\right)$$
(9)

The Langevin's parameter ξ is a measure of the dimensionless field strength. Neglecting the strong magnetic field $\xi > 1$ and τ_s as per Shukla and Kumar (1987), the equation (9) can be approximated as

$$\bar{M} = \frac{M_0}{H} \Big[\bar{H} + \bar{\tau} \left(\bar{\Omega} \times \bar{H} \right) \Big], \tag{10}$$

Where

$$\overline{\tau} = \frac{\tau_B}{1 + \frac{\mu_0 \tau_B \tau_s}{I} M_0 H} M_0 = n\mu \left(\coth \xi - 1/\xi \right) \text{ and } H = k_B T \xi / \left(\mu_0 \mu \right), \tag{11}$$

with $\frac{I}{\tau_s} = 6\eta\varphi$ and $\tau_B = 3\eta V / (k_B T)$, where $\varphi = nV$ stands for the volume concentration of the

particles, k_B is the Boltzmann constant, n be the number of particles per unit volume, T is the temperature and μ being the magnetic moment of a particle for spherical particles in suspension (Shliomis, 1972).

One can express $\overline{\tau}$ as

$$\overline{\tau} = \frac{6\eta\varphi}{nk_B T \left(1 + \xi \coth\xi\right)} \tag{12}$$

With uniform magnetic field $\overline{H} = (0,0,H_0)$ and radial velocity component *u* in axially symmetric flow, equation (8) and (10) turns out to be

$$\frac{\partial^2 u}{\partial z^2} = \frac{1}{\eta \left(1 + \frac{\mu_0 M_0 H_0 \overline{\tau}}{4\eta}\right)} \frac{dp}{dr}$$
(13)

From equations (11-13), one obtains

$$\frac{\partial^2 u}{\partial z^2} = \frac{1}{\eta \left(1+\tau\right)} \frac{dp}{dr}$$
(14)

Where

$$\tau = \frac{3}{2}\varphi \frac{\xi - \tanh \xi}{\xi + \tanh \xi}$$
(15)

Solving equation (14) under the boundary conditions with slip

$$u = 0$$
 when $z = 0$, $u = -\frac{1}{s} \frac{\partial u}{\partial z}$ when $z = h$ with $\frac{1}{s}$ as a slip parameter.

One can derive

$$u = -\frac{1}{\eta_a} \frac{z^2 - zsh(z - h)}{2(1 + sh)} \frac{dp}{dr}$$
(16)

Where $\eta_a = \eta (1 + \tau)$

Substituting the above value of u in the integral form of the continuity equation

$$\frac{1}{r}\frac{d}{dr}\int_{0}^{h}rudz + w_h - w_0 = 0$$

yields

$$\frac{1}{r}\frac{d}{dr}\left(\frac{h^3r(2+sh)}{1+sh}\frac{dp}{dr}\right) = 12\eta_a\left(w_h - w_0\right)$$
(17)

With the Einstein's viscosity of the suspension $\eta = \eta_0 \left(1 + \frac{5}{2}\varphi\right)$ where the viscosity of carrier liquid η_0 (Shliomis, 1972)) and

$$\eta_a = \eta \left(1 + \tau \right) = \eta_0 \left(1 + \frac{5}{2} \varphi \right) \left(1 + \tau \right) \tag{18}$$

equations (17-18) take the form

$$\frac{1}{r}\frac{d}{dr}\left(\frac{h^{3}r(2+sh)}{1+sh}\frac{dp}{dr}\right) = 12\eta_{0}\left(1+\frac{5}{2}\varphi\right)(1+\tau)(w_{h}-w_{0})$$
(19)

As per the discussion of Bhat (2003), the conditions for the lower surface is solid and the porous facing of thickness H^* at the upper surface are,

$$w_0 = 0 \text{ and } w_h = \dot{h}_0 - \frac{k}{\eta_a} \frac{\partial P_1}{\partial z}$$
 (20)

Where \dot{h}_0 is the squeeze velocity, P_1 be the pressure in the porous region and permeability of the porous region \bar{k} .

Pressure P_1 satisfies the equation

$$\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial P_1}{\partial r}\right) + \frac{\partial^2 P_1}{\partial z^2} = 0$$
(21)

Using the Morgan-Cameron approximation,

$$\left(\frac{\partial P_1}{\partial z}\right)_{z=h} = \frac{H^*}{r} \frac{d}{dr} \left(r\frac{dp}{dr}\right)$$
(22)

Using equation (20) and (22), equation (19) yields

$$\frac{1}{r}\frac{d}{dr}\left(\frac{h^3r(2+sh)}{1+sh}\frac{dp}{dr}\right) = 12\eta_0\left(1+\frac{5}{2}\varphi\right)\left(1+\tau\right)\left(\dot{h}_0 - \frac{\bar{k}}{\eta_a}\frac{H^*}{r}\frac{d}{dr}\left(r\frac{dp}{dr}\right)\right)$$
(23)

Solving the above equation, one can find

$$\frac{1}{r}\frac{d}{dr}\left(\left[\frac{h^3\left(2+sh\right)}{1+sh}+12\bar{k}H^*\right]r\frac{dp}{dr}\right) = 12\eta_0\left(1+\frac{5}{2}\varphi\right)\left(1+\tau\right)\dot{h}_0\tag{24}$$

Upon establishment of the non-dimensional measures:

$$R = \frac{r}{b}, \bar{h} = \frac{h}{h_0}, \bar{\beta} = \beta b^2, P = \frac{-h_0^3 p}{\eta_0 b^2 \dot{h}_0}, \ \bar{s} = sh_0, \psi = \frac{\bar{k}H^*}{h_0^3}, k = \frac{a}{b}$$
(25)

and use of equation (25), Equation (24) reduces to

$$\frac{1}{R}\frac{d}{dR}\left\{\left[\frac{\overline{h^{3}}\left(2+\overline{sh}\right)}{1+\overline{sh}}+12\psi\right]R\frac{dP}{dR}\right\} = -12\eta_{0}\left(1+\frac{5}{2}\varphi\right)\left(1+\tau\right)$$
(26)

Solving Equation (26) subject to Reynolds boundary conditions for the bearing

$$P(1) = P(k) = 0 (27)$$

k < DD

One can get the dimensionless pressure P as

$$P = \int_{1}^{R} \left(-\frac{6E}{G} \right) R dR + c_1 \int_{1}^{R} \left(\frac{1}{GR} \right) dR$$
(28)

where

$$E = \left(1 + \frac{5}{2}\varphi\right)\left(1 + \tau\right), G = \frac{\overline{h^3}\left(2 + \overline{sh}\right)}{1 + \overline{sh}} + 12\psi, c_1 = \frac{\int\limits_{1}^{\infty} \frac{6ER}{G}dR}{\int\limits_{1}^{k} \frac{1}{GR}dR}$$
(29)

The load-carrying capacity of the bearing can be found in non-dimensional form as

$$\overline{W} = \frac{-h_0^3 W}{2\pi\eta_0 b^4 \dot{h}_0} = \int_1^k RP dR = \frac{-1}{2} \int_1^k R^2 \frac{dP}{dR} dR - \frac{1}{2} \left(\int_1^k -\frac{6ER^3}{G} dR + c_1 \int_1^k \frac{R}{G} dR \right)$$
(30)

3. Results and Discussion

In section 2, we have analyzed the mathematical relations for the considered problem. Here, graphical results are discussed.

Here the equation (28) describes the non-dimensional pressure distribution, while equation (30) determines the dimensionless load carrying capacity (LCC). As compared with the conventional lubricants, this study tends to point out that the dimensionless pressure increases by

$$\left(1+\frac{5}{2}\varphi\right)\tau\int_{R}^{1}\frac{6R}{G}dR$$

while the non-dimensional LCC increases by

$$\left(1+\frac{5}{2}\varphi\right)\tau\int_{1}^{k}\frac{3R^{3}}{G}dR$$

due to the linearity of the magnetization parameter in both the expression.

Considering $\frac{1}{s} \to 0$ and $\psi \to 0$, one can find the effect of the Shliomis model-based magnetic fluid in squeeze film annular bearing. Further, taking $\tau \to 0$, this analysis reduces to the

study of annular plates without lubrication (Gupta and Vora, 1980)). Moreover, this investigation is the extension of the study carried out by Shah and Bhat (2005), including the combined influence of porosity and velocity with slip at surfaces. The graphical representations of the problem are presented in Figures (2) to (10).

Figures (2) to (4) describe the variation of non-dimensional LCC concerning for Shliomis model-based magnetic parameter for different values of ϕ , $\overline{\beta}$, ψ and $\frac{1}{s}$ respectively. From Figures (2) to (4), one can find that the LCC enhances sharply with increasing magnetic parameter τ . But (3) and (5) indicate that the effect of $\overline{\beta}$ and $\frac{1}{s}$ with respect to τ is not up to mark so far as the LCC is concerned.



Fig. 2. Profile of LCC for τ and ϕ with $\frac{1}{\sqrt{s}} = 0.02$, $\psi = 25$, $\overline{\beta} = 1.5$.



Fig. 3. Profile of LCC for τ and $\overline{\beta}$ with $\frac{1}{\sqrt{s}} = 0.02$, $\psi = 25$, $\phi = 0.1$.



Fig. 4. Profile of LCC for τ and ψ with $\frac{1}{s} = 0.02 \ \phi = 0.1$, $\overline{\beta} = 1.5$.



Fig. 5. Profile of LCC for τ and $\frac{1}{s}$ with $\psi = 25$, $\phi = 0.1$, $\overline{\beta} = 1.5$.

The distribution of the LCC regarding ϕ for different values of $\overline{\beta}$, ψ and $\frac{1}{s}$ is presented in Figures(6) – (8). It is noticed that ϕ decreases the LCC while the effect remains the same for $\frac{1}{s}$ and $\overline{\beta}$ increases LCC marginally.



Fig. 6. Profile of LCC for ϕ and $\frac{1}{s}$ with $\psi = 25$, $\tau = 0.1$, $\overline{\beta} = 1.5$.



Fig. 7. Profile of LCC for ϕ and $\overline{\beta}$ with $\psi = 25$, $\tau = 0.1$, $\frac{1}{\sqrt{s}} = 0.02$.



Fig. 8. Profile of LCC for ϕ and ψ with $\frac{1}{s} = 0.02$, $\tau = 0.1$, $\overline{\beta} = 1.5$.

From Figures (9) and (10), one can see the profile for the LCC concerning $\overline{\beta}$. for the different values of ψ and $\frac{1}{s}$. The influence of LCC regarding $\overline{\beta}$ and ψ has negligible effect

as displayed in Figures (9). Although, the LCC increases with increasing the value of $\overline{\beta}$ with respect to $\frac{1}{s}$ as per figure (10).



Fig. 9. Profile of LCC for $\overline{\beta}$ and ψ with $\frac{1}{s} = 0.02$, $\tau = 0.1$, $\phi = 0.1$.



Fig. 10. Profile of LCC for $\overline{\beta}$ and $\frac{1}{s}$ with $\psi = 25, \tau = 0.1, \phi = 0.1$

Figure (11) depicts the variation of LCC with respect to ψ for various values of $\frac{1}{s}$. The rate of decrease in the LCC due to ψ is quite sharp.



Fig. 11. Profile of LCC for ψ and $\frac{1}{s}$ with $\overline{\beta} = 1.5$, $\tau = 0.1$, $\phi = 0.1$.

From the graphical representation, one can suggest that the negative effect of slip velocity can be compensated by the magnetization parameter τ with the inclusion of the proper selection of other parameters. In general, the bearing can sustenance a load even if there is no flow.

4. Validation

The comparison of our study with the investigation of Shah and Bhat (2005) is discussed herein following tables to validate our research.

	τ	0.1	0.2	0.3	0.4	0.5
Shah and Bhat (2005)	0.01	4.102285498	4.202341242	4.302396986	4.40245273	4.502508474
Present Study	н Ф	6.01259653	6.159245226	6.305893922	6.452542617	6.599191313
Shah and Bhat (2005)	0.01	4.475220544	4.584372264	4.693523985	4.802675705	4.911827426
Present Study	н ф	6.559196214	6.71917661	6.879157005	7.039137401	7.199117796
Shah and Bhat (2005)	0.01	4.848155589	4.966403286	5.084650984	5.202898681	5.321146378
Present Study	н ф	7.105795899	7.279107994	7.452420089	7.625732184	7.799044279
Shah and Bhat (2005)	0.01	5.221090634	5.348434308	5.475777982	5.603121656	5.73046533
Present Study	н Ф-	7.652395583	7.839039378	8.025683173	8.212326968	8.398970762
Shah and Bhat (2005)	$\phi = 0.01$	5.59402568	5.73046533	5.866904981	6.003344632	6.139784283
Present Study		8.198995268	8.398970762	8.598946257	8.798921751	8.998897245

Table 1. Profile of *W* for τ and ϕ .

	τ	0.1	0.2	0.3	0.4	0.5
Shah and Bhat (2005)	= 1.5	2.433675036	5.887540886	14.43968034	35.87446052	90.16334551
Present Study	ι. 	3.021753265	3.025973857	3.029069025	3.031342056	3.033013821
Shah and Bhat (2005)	$\bar{\beta} = 1.6$	2.654918221	6.422771876	15.75237856	39.13577511	98.36001329
Present Study		3.296458107	3.301062389	3.304438936	3.306918606	3.30874235
Shah and Bhat (2005)	$\bar{\beta} = 1.7$	2.876161406	6.958002865	17.06507677	42.39708971	106.5566811
Present Study		3.57116295	3.576150922	3.579808848	3.582495157	3.584470879
Shah and Bhat (2005)	$\bar{\beta} = 1.8$	3.097404592	7.493233855	18.37777498	45.6584043	114.7533488
Present Study		3.845867792	3.851239454	3.855178759	3.858071707	3.860199408
Shah and Bhat (2005)	$\bar{\beta} = 1.9$	3.318647777	8.028464845	19.69047319	48.91971889	122.9500166
Present Study		4.120572634	4.126327987	4.13054867	4.133648258	4.135927938

Table 2. Profile of W for τ and $\overline{\beta}$.

A comparison of the present study with the ones mentioned above indicates that the porous and slip effect may influence bearing's performance by selecting the proper range of both the parameters. Perhaps, this could be due to the positive characteristic of the magnetization parameter and ϕ (Table 1).

A comparison concerning Table 2 shows that the present study is more preferable for the initial values of magnetization parameters, but if it increases, performance will also be remarkable in the previous study with respect to the upper plate's curvature parameter.

5. Conclusions

The load lifting capacity increases when the solid phase's volume concentration and the curvature parameter are increased. From the present theoretical study, the Shliomis model is more effective than Neuringer-Rosenweig's model due to Ferro particles' rotation and moments. The load capacity of annular squeeze film can be made ideal by a proper choice of curvature parameter of the upper plate, slip velocity and porosity. The present study may lead to a new scope toward the optimal performance of the bearing system.

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